

Appendix 3

CALCULATION PROCESS

```
5  /*
 * Channel communicating object positions
 */ chap unsigned 17 position;

/*
10 * Channel communicating segment information
*/
chanout unsigned 9 segment;

/*
15 * Channel communicating button information
*/
chanin unsigned 2 buttons;

/*
20 * Overall par
*/
par

/*
25 * Mass motion
*/
par

/*
 * Positions of each mass, 9+8 fixed point
*/
30 unsigned 17 p0, p1, p2, p3, p4, p5, p6, p7;
/*

```

```
* Velocity of each mass, 9+8 fixed point
*/
int 17 v1, v2, v3, v4, v5, v6, v7; /*

5      * Accelerations of each mass, 9+8 fixed point
*/
int 17 a1, a2, a3, a4, a5, a6, a7; /*

* Sutton status
*/
10     unsigned 2 button status;
/*
* Initial setup of positions
*/
15     p0 = 65536;
p1 = 65536;
p2 = 65536;
p3 = 65536;
p4 = 65536;
20     p5 = 65536;
p6 = 65536
p7 = 65536

25     /*
* Forever
*/
while (1)
{
30     /*

```

```
  * Send successive positions down position channel
  */
send(position, p0);
send(position, p1);
5    send(position, p1);
send(position, p2);
send(position, p2);
send(position, p3);
send(position, p3);
10   send(position, p4);
send(position, p4);
send(position, p5);
send(position, p5);
send(position, p6);
15   send(position, p6);
send(position, p7);

/*
* Update positions according to velocities
20   */
p1 +_ (unsigned 17)vl;
p2 +_ (unsigned 17)v2;
p3 +_ (unsigned 17)v3;
p4 +_ (unsigned 17)v4;
25   p5 +_ (unsigned 17)v5;
p6 +_ (unsigned 17)v6;
p7 +_ (unsigned 17)v7;

/*
* Update velocities according to accelerations
30   */

```

```
    v1 += a1 - (v1 » 6);
    v2 += a2 - (v2 » 6);
    v3 += a3 - (v3 » 6);
    v4 += a4 - (v4 » 6);
5      v5 += a5 - (v5 » 6);
    v6 += a6 - (v6 » 6);
    v7 += a7 - (v7 » 6);

    /*
10   * Set accelerations according to relative positions
    */
    a1 = (int 17)((p2 » 8) - (p1 » 8)) + ((p0 » 8) - (p1 » 8));
    a2 = (int 17)((p3 » 8) - (p2 » 8)) + ((p1 » 8) - (p2 » 8));
    a3 = (int 17)!!(p4 » 8) - (p3 » 8)) + ((p2 » 8) - !p3 » 8));
15   a4 = (int 17)((p5 » 8) - (p4 » 8)) + ((p3 » 8) - (p4 » 8));
    a5 = (int 17)((!p6 » 8) - (p5 » 8)) + ((p4 » 8) - (p5 » 8));
    a6 = (int 17)((p7 » 8) - (p6 » 8)) + ((p5 » 8) - (p6 » 8));
    a7 = (int 17)((p6 » 8) - (p7 » 8));

20   /*
    * Get button information
    */
    receive(buttons, button status);

    /*
25   * Fix top point according to buttons
    */ if (button status & 1)

    p0 = 65536 - 16384;
30      )
    else      if (button status & 2)
```

```
(  
    -  
    p0 = 65536 + 16384;  
  
else  
5  
    p0 = 65536;  
    }  
)  
/*  
10    * nine drawing  
    */  
(  
    /*  
     * Positions of previous and next massess positions  
15    */  
    unsigned 17 prev_.pos, next pos, curr pos;  
    /*  
     * Which line of interpolation  
     */  
20    unsigned char line;  
    /*  
     * Forever  
     */  
    while (1)  
25    (  
        /*  
         * Receive previous mass position  
         */  
        receive (position, prev posy;  
30        curr pos = prev pos;  
        /*
```

```
* Read next mass position
*/
receive(position, next posy;
/*
5
* Do 64 lines of interpolation
*/
for (line = 0; line != 64; line++)
(
/*
10
* Send start position of segment
*/
send(segment, curr pos >> 8); /*width adjustment:17 along
channel of width 9 so takes bottom
9 bits*/
15
/*
* Move by appropriate amount (1/64 total change)
*/
curr pos +_ (unsigned 17)((int 17)next pos -
20
(int 17)prev pos) >> 6);
/*
* Send end position of segment
*/
send(segment, curr pos >> 8);
25
)
)
)
)
30
```

DISPLAY PROCESS

```
/* standard includes */
    #include "hammond.h"
5     #include "syncgen.h"
    #include "stdlib.h"
    #include "parallel.h"

    /*
10    * Segment information channel */ chap segment;

    /*
* Button information channel */
chan buttons:
15
    /
* Include dash generated stuff */
#include "handelc.h"

20      /*
* Main program */
void main() (
    /
* Scan positions
25    */ unsigned sx, sy;

    /
* Vdeo output register
*/
30    unsigned 1 video;
```

```
/*
 * Video output bus
 */

5   interface bus out() video out(Visible(sx, sy) ?
(video ? (unsigned 12)Oxffff : 0) 0) with video spec;

#ifndef SIMULATE
/*
10  * Left button input bus
*/
interface bus in (unsigned 1) button_left()
    with button_white spec;

15  /*
 * Right button input bus
*/
interface bus in(unsigned 1) button_right()
    with button_black spec;
20  #endif

/*
*
Overall par
25  */ par {
/*
    * VGA sync generator
*/
    SyncGen(sx, sy, hsync pin, vsync pin);
30  /*
*

```

Dash generated hardware

```
/*
hardware();
/*
5   * Run-length decoder
/*
{
/*
  * Segment start and end positions
10  */
unsigned start, end;
/*
  * Forever
/*
15  while (1)
{
  while (sy != 448)
  /*
    * Read segment information
20  */
    segment ? start;
    segment ? end;
  /*
    * Get in the right order
25  */
    if (start > end)
    {
      par
      {
30  end = start;
```

```
start = end;.  
)  
  
5          /*  
 * Make at least 1 pixel visible  
 */  
if (start == end)  
    end++;  
  
10         /*  
 * Wait  
 */  
while (sx != 0)  
    delay;  
  
15         /*  
 * Draw a scanline worth  
 * /  
while (sx != 512)  
    if ((sx < - 9) >= start && (sx < - 9) < end)  
  
        video = 1;  
    else  
        video = 0;  
  
25         )  
/*  
 * Communicate button status  
 */  
30         #ifdef SIMULATE  
        buttons ! 1;
```

```
#else
    buttons ! button left.in @ button right.in;
#endif
/*
 * Wait
 */
while (sy != 0)
    delay;
)
```